

APPLICATION UNDER UNITED STATES PATENT LAWS

Invention: BI-DIRECTIONAL SCAN SWITCH MATRIX METHOD AND APPARATUS

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This is a:

- Provisional Application
- Regular Utility Application
- Continuing Application
- PCT National Phase Application
- Design Application
- Reissue Application
- Plant Application

SPECIFICATION

BI-DIRECTIONAL SCAN SWITCH MATRIX

METHOD AND APPARATUS

BACKGROUND OF THE INVENTION

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1. Field of the Invention

This invention relates to electronic input devices. More particularly, it relates to a multi-element switch matrix in which each rows and columns may be bi-directionally scanned to provide high input capacity.

2. Background of Related Art

A keypad may be one of the most common user interfaces to electronic equipment, e.g., a computer, a TV, or a VCR, etc. Typically, a keypad, e.g., on a computer keyboard or on a TV remote controller, includes a plurality of keys arranged in a matrix of rows and columns. A computer user or a TV viewer may input their commands to and/or interact with the computer or the TV by pressing a particular key among a plurality of keys on a keypad.

Typically, the pressing of a key mechanically moves one or more corresponding electrical contact(s) to come into physical contact with another, thereby making an electrical connection between them. Depending on the type of connection mechanism employed, the electrical connection may be only momentary (e.g., may be disconnected when the key is released) or can be persistent (e.g., may remain connected even after releasing of the key until deliberately disconnected, e.g., by pressing the key again).

One example of connection mechanism that provides a momentary electrical connection is a push button, which provides electrical connection only while a button is being pressed, and

disconnects when pressing is discontinued. On the other hand, a switch, once turned on, e.g., by pressing a key, remains on (i.e., connected) even if the key is released, until the switch is actively turned off, e.g., by pressing the key again, as is the case with a particular kind of switch
5 called a toggle switch.

As with the keys, the corresponding connection mechanisms are also arranged in a matrix of rows and columns, typically referred to as a switch matrix. Thus, the position of each push button or switch within the matrix can be represented by a row and column coordinate, e.g., (row,
10 col). For example, a push button located on the second row and at third column would have the coordinate (2, 3).

Typically, a switch matrix is "scanned" to determine which key is pressed. The scanning typically involves applying a known signal to a row, and examining each column. For example, if a signal level LOW
15 was detected in column 2 while row 1 is being driven LOW, then the key at coordinate (1, 2) is determined as being pressed. This process is repeated for each of the rows, one row at a time, at a sufficiently rapid speed to detect even the briefest pressing of a key. With this scanning method, pressing of any key at any position within the matrix can be
20 detected so long as only one key is pressed at a time.

As more and more advanced features are added to electronic equipment, the user interface thereto requires increasing number of keys. Unfortunately, the maximum number of keys a conventional switch matrix may scan and detect is limited to the product of
25 the number of rows and the number of columns. For example, a conventional 4x4 switch matrix would support a maximum of 16 keys.

Thus, the size of conventional matrix must increase in order to accommodate increasing required number of keys, thus increasing the manufacturing cost of user interface devices.

Furthermore, a conventional scanning switch matrix can only accommodate momentary contact connection mechanisms, e.g., push buttons. Because a switch remains connected even after the release of the corresponding key, a sequential pressing of two keys would appear to 5 a conventional scanning switch matrix as if the two keys were pressed simultaneously. Because a conventional scanning switch matrix can only detect one key press at a time, it cannot accommodate a switch.

Thus, if a user interface device requires both push buttons and switches, a dedicated detection mechanism must be provided for 10 each switch in addition to the switch matrix. The additional detection mechanism adds complexity and cost to the user interface.

There is a need for a scanning switch matrix that is capable of accommodating more keys than the conventional maximum, i.e., the product of the number of rows and the number of columns.

15 There is also a need for more flexible and cost efficient switch matrix that allows integration of switches without the need for dedicated detection mechanism for the switches.

SUMMARY OF THE INVENTION

20 In accordance with the principles of the present invention, a switch matrix comprises at least one row conductor and at least one column conductor. At least one of the at least one row conductor and the at least one column conductor is capable of being driven with a predetermined voltage level, and is capable of having a voltage level read 25 therefrom during a scanning of the switch matrix.

In accordance with an aspect of the principles of the present invention, a switch matrix comprises a plurality row conductors, a plurality of column conductors; and a plurality of switching elements adapted to connect at least one of the plurality of row conductors to at least one of 30 the plurality of column conductors. The total number of switching elements

of the plurality of switching elements exceeds a product of a total number of row conductors of the plurality of row conductors and a total number of column conductors of the plurality of column conductors.

In accordance with another aspect of the principles of the present invention, a switch matrix comprises a plurality of row conductors, a plurality of column conductors, at least one switching element adapted to momentarily connect at least one of the plurality of row conductors to at least one of the plurality of column conductors; and at least one switching element adapted to persistently connect at least one of the plurality of row conductors to at least one of the plurality of column conductors.

In accordance with the principles of the present invention, a method of scanning a switch matrix comprises, driving one at a time at least one of a plurality of row conductors with a predetermined voltage level, monitoring each of a plurality of column conductors while one of the plurality of row conductors is being driven with the predetermined voltage level, driving one at a time at least one of a plurality of column conductors with a predetermined voltage level, and monitoring each of a plurality of row conductors while one of the plurality of column conductors is being driven with the predetermined voltage level.

In accordance with yet another aspect of the present invention, a switch matrix may be scanned without the need of fast switching signals being present in the row and column conductors, thus eliminating the need for a AC de-coupling, or a noise and/or EMI filtering capacitor.

BRIEF DESCRIPTION OF THE DRAWINGS

Features and advantages of the present invention will become apparent to those skilled in the art from the following description with reference to the drawings, in which:

Fig. 1 is a simplified schematic of an exemplary 3x3 switch matrix, in accordance with the principles of the present invention.

Fig. 2 is a simplified schematic of an exemplary 3x3 switch matrix having integrated switches, in accordance with the principles of the present invention.

Fig. 3 is a flow chart showing the scanning of the exemplary 3x3 switch matrices shown in Figs. 1 and 2, in accordance with the principles of the present invention.

Fig. 4 is a simplified schematic of an exemplary hardware implementation of the scanning of the 3x3 switch matrix, in accordance with the principles of the present invention.

Fig. 4A is a timing diagram of scanning cycle of an exemplary 3x3 switch matrix shown in Fig. 4, in accordance with the principles of the present invention.

Fig. 5 is a simplified schematic of an exemplary hardware implementation of the scanning of the 3x3 switch matrix having integrated switches, in accordance with the principles of the present invention.

Fig. 6 is a simplified schematic of an exemplary conventional 3x3 switch matrix.

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DETAILED DESCRIPTION OF ILLUSTRATIVE EMBODIMENTS

The present invention provides a flexible and efficient switch matrix and scanning method thereof usable in user interface devices, e.g., a keypad or the like, having a number of connection mechanisms, e.g., push buttons and/or switches. A switch matrix device and scanning method thereof in accordance with the principles of the present invention is capable of accommodating a number of connection mechanisms up to twice the product of the number of rows and the number of columns.

A switch matrix device and scanning method thereof allows integration of one or more switches in the switch matrix without the need for additional detection mechanisms dedicated to the switches.

While, for the sake of brevity and clarity, an exemplary 5 matrix having three (3) rows and three (3) columns, i.e., 3x3 switch matrix is described, the present invention is equally applicable to matrixes of any size, i.e., having any number of rows or any number of columns, and equally applicable to symmetrical matrixes, i.e., having equal number of rows and columns, as well as unsymmetrical matrixes.

10 Fig. 6 shows a simple exemplary conventional switch matrix with nine (9) connection mechanisms arranged as a matrix of three (3) rows and three (3) columns.

In particular, Fig. 6 shows nine (9) push buttons, K1-K9. Each of the nine push buttons K1-K9 has a pair of electrical contacts 33 15 and 34, and a connection button 35. Each electrical contact 33 is connected to a row conductor 31 while each electrical contact 34 is connected to the column conductor 32. The push buttons on the same column or on the same row share the same column conductor 32 or the same row conductor 31, respectively. For example, push buttons K1, K2 20 and K3 share the same row conductor 31 of Row 1 while push buttons K1, K4 and K7 share the same column conductor 32 of Col. 1.

In order to detect a push button being pressed, an algorithm is provided to scan each of the push buttons. During the scanning, a unique signal is applied to one row at a time and each of the columns is 25 monitored for the presence of the unique signal. This process is repeated for each row, one at a time, on a rapid basis to ensure that even the briefest closure of a connection mechanism will be detected.

When the unique signal is applied to a particular row, the other rows are connected to a different voltage by high impedance to 30 prevent excessive currents in the event that more than one switch in a

column is depressed. In a typical conventional circuit, the rows may be driven low and the columns are passively pulled high to a voltage level, e.g., to VCC or VDD, above the switching threshold of a monitoring circuitry, e.g., an input receiver of a controller (not shown).

5 When contacts 34 and 35 are disconnected (i.e., when the button 35 is not pressed), the column conductor 32 remains unconnected from the row conductor 31. Thus, the voltage at the input of the receiver 36 remains high (e.g., at VDD), or at high impedance (e.g., tri-stated, Hi-Z). However, when the button 35 is pressed to bring the contacts 33 and
10 34 into an electrical connection, the conductors 31 and 32 are connected to each other. If conductor 31 is driven low, the voltage at the input receiver of the controller would be driven low. Thus, pressing of any push buttons K1-K9 can be detected by driving each row LOW, and monitoring for a LOW voltage at each column,

15 ~~For example, assume that the push button K5 (and no other push button at the same time) is pressed. The scanning algorithm would first drive Row 1 Low (and drive Rows 2 and 3 HIGH or high impedance (i.e., tri-stated output), and check the voltage levels of each of columns Col. 1 – Co. 3, one column at a time. Because the push buttons K1-K3~~
20 were not pressed, a high voltage level, e.g., VDD, or a high impedance voltage level would be detected at each of columns ~~Col. 1 – Col. 3.~~

The algorithm would then drive Row 2 LOW (and drive Rows 1 and 3 HIGH), and check the voltage levels of each of columns Col. 1 – Co. 3, one column at a time. Because the push buttons K4 and
25 K6 were not pressed, a high voltage level, e.g., VDD, would be detected at each of columns Col. 1 – Col. 3. However, because Row 2 would be driven LOW, a LOW voltage would be detected at Col. 2 through the connection made between conductor 31 and conductor 32 via the connections between contacts 33 and 34 due to pressing of the button 35
30 at the push button K5.

When Row 3 is driven LOW by the algorithm, and Col. 1-Col. 3 are monitored, a HIGH voltage level or High Impedance level would be detected at each of the columns. Thus, a determination can be made that the push button K5 was pressed by the fact that LOW voltage was
5 detected only at the coordinate (2, 2), corresponding to the position of the push button K5.

Because of the sequential switching (e.g., from LOW to HIGH) at each of the coordinates, a very High frequency AC signal may be carried by each of the conductors 31 and 32. The AC signals typically
10 results in noise signals which must be minimized by the use of a low impedance AC shunt to ground for each row conductor 31 and column conductors 32 through an EMI capacitor 39. Thus, in a conventional switch matrix, the use of the AC de-coupling (or EMI and/or noise filter) capacitor 39 is required for a proper operation.

15 Furthermore, it can be appreciated that the above-described conventional switch matrix requires that each crossing of a row and column conductors 31 and 32 has a single unique coordinate (Row, Column). That is any pair of a row conductor and a column conductor may be assigned one unique coordinate. Thus, for example, a pair of
20 second row and third column would have a coordinate (2, 3). Thus, a conventional switch matrix can accommodate a maximum of rows x columns (e.g., 9 in the above 3x3 matrix example) of switching elements, e.g., buttons or keys, each button or key being uniquely addressable by the coordinate (Row, Column).

25 In contrast, the switch matrix 10 in accordance with the principles of the present invention shown in Fig. 1 may accommodate up to twice the size of the matrix, i.e., 2 x rows x columns, of push buttons, doubling the capacity of a conventional switch matrix. As will be explained, each crossing (or pair) of a row and a column can have two

unique coordinates, e.g. (Row, Column) and (Column, Row), thus can support up to two push buttons, each being uniquely addressable.

In particular, the switch matrix shown in Fig. 1 has two push buttons and a blocking diode **12** at each coordinate. Thus, the 3x3 switch matrix of Fig. 1 has 18 push buttons **KA-KI** and **K1-K9**, i.e., twice the product of the numbers of rows and columns.

Although the blocking diode **12** is shown in this example as being connected between switching elements **KA-KI** and the respective row conductor **31**, it should be readily apparent to one of ordinary skill that
10 the diode may be placed in other places, e.g., between the switching elements **KA-KI** and the respective column conductors **32**, or between switching elements **K1-K9** and either the row conductors **31** or the column conductors **32** so long as it becomes forward biased when a respective row is driven LOW or when a respective column is driven LOW, but not
15 when the respective row and column are both driven LOW.

Unlike a conventional switch matrix, the switch matrix in accordance with the principles of the present invention allows monitoring voltage levels of both the row conductors **31** and the column conductors **32**. Moreover, unlike a conventional switch matrix, the switch matrix of
20 Fig. 1 allows driving both the row conductors **31** and the column conductors **32**. That is, both the row conductors **31** and column conductors **32** of the switch matrix in accordance with the principles of the present invention are bi-directional, and can be either an input or an output, at any given time.

25 The blocking diode **12** is reverse biased when the respective row conductor is driven LOW, and the corresponding switching element, e.g., the corresponding push button **KA-KI** is connected. Thus, even if the respective switching element **KA-KI** is connected, the corresponding row conductor **31** and the column conductors **32** remain disconnected to
30 each other.

However, when a respective column is driven LOW, and the corresponding switching element **KA-KI** is connected, the diode **12** is forward biased, and thus the corresponding row conductor **31** and the column conductor **32** are connected. When columns are being driven, the
5 voltage driven on the column conductor **32** (less the forward bias voltage drop over the diode which is typically on the order of half a volt) will be placed on the row conductor **31** if the corresponding switching element **KA-KI** is connected. Thus, by monitoring the voltage level of the respective row conductor, a closure of a switch element **KA-KI** may be
10 detected.

Thus, it can be appreciated that closure of a switching element **K1-K9** can be detected by driving each row, one at a time, and monitoring each of the columns. Because the diode **12** is reverse biased when a row conductor **31** is driven LOW, any closure of switching
15 elements **KA-K9** would not have any effect on the monitored voltages of any of the column conductors **32**. During this forward scanning (labeling only as a convenience, scanning where only the rows are driven will be referred hereafter as a forward scan, and scanning where only the columns are being driven will be referred as a reverse scan), closure of
20 any of switching elements **K1-K9** can be detected.

During a reverse scan, when a column conductor is driven LOW, the corresponding diode **12** will be forward biased when the corresponding switching element **KA-KI** is connected, and thus any closure of switching elements **KA-KI** can be made as described
25 previously.

Thus, during a forward scan, coordinates can be expressed as (Row, Column) as was the case with a conventional switch matrix. However, during a reverse scanning, a coordinate (Column, Row) may be provided. Unlike a conventional switch matrix, in a switch matrix in

accordance with the principles of the present invention, a coordinate (Row, Column) is unique from a coordinate (Column, Row).

For example, in a conventional switch matrix, a coordinate (Row =2, Column = 3) and a coordinate (Column = 3, Row = 2) describe 5 the same switching element, namely **K6**, i.e., the one present at the crossing of the second row conductor and the third column conductor. In a switch matrix in accordance with the principles of the present invention, a coordinate (Row =2, Column = 3) and a coordinate (Column = 3, Row = 2) describe two different switching elements, namely **K6** and **KF**, 10 respectively.

By alternating a forward scan and a reverse scan in one scanning cycle as shown in Fig. 1A, all eighteen switching elements can be monitored for their closure.

Fig. 2 shows another exemplary switch matrix having 15 integrated persistent connection switches, in accordance with the principles of the present invention.

In particular, Fig. 2 shows a switch matrix **20** identical to switching matrix as Fig. 2 in every respect but having persistent connection switches **SWA-SWC** in three coordinates of the **column 1** in 20 stead of the push buttons **KA**, **KD** and **KG**.

The switch matrix **20** operates essentially as the switching matrix **10** of Fig. 1 despite the inclusion of the switches **SWA-SWC**.

For example, during a forward scan, the switches **SWA-SWC** would not have any affect on the switching matrix because as with 25 switching matrix **10**, the diodes **12** would be reverse biased, and the switches would be isolated from the row and column conductors.

During a reverse scan, because only one column driver **37'** is enabled at a time, and only one row receiver is read at a time, each of the switches **SWA-SWC** can be uniquely monitored to detect their 30 closure.

For example, when **column 1** is driven LOW, and the receiver of **row 1** is read LOW, then the switch **SWA** must be closed, regardless of the status of other switches **SWB** and **SWC**. Thus, closure of any switches **SWA-SWC** can be uniquely detected.

5 It can thus be appreciated that persistent connection type switching elements can be integrated into the same switching matrix alongside temporary connection type switching elements scanned with the same scanning algorithm, without requiring a dedicated scanning or detection mechanism for either the persistent connection or the temporary
10 connection type switching elements.

Fig. 3 shows a flow chart of scanning algorithm usable with the exemplary embodiments of the switch matrices according to the principles of the present invention as shown in Figs. 1 and 2.

In particular, during forward scanning steps 301-309, each
15 of the row conductors 31 is driven LOW (i.e., walking a zero), and the column conductors 32 are monitored one at a time to detect the closure, if any, of switch elements **K1-K9** as previously described. More particularly, in step 301, the first row and the first column, for example, are chosen as the starting point of the forward scan. It should be apparent to and
20 understood by one having an ordinary skill that the starting point need not be the coordinate (1,1), and may be any other coordinate. As shown in steps 304-307, each of the columns 1 to n (e.g., 1 to 3 in 3x3 switch matrices as shown in the examples of Figs. 1 and 2) are monitored (in step 305) while each row **i** is driven LOW (step 303). In step 306, a
25 determination is made whether or not all columns have been monitored (or read) by comparing the current column **j** with the maximum number of columns **n**, e.g., 3 in the examples of Figs. 1 and 2). In step 308, a determination is made whether or not all rows had been driven LOW by comparing the current row **i** with the maximum number of rows **n**, e.g., 3
30 in the examples of Figs. 1 and 2).

During a reverse scanning steps 310-318, each of the column conductors 32 is driven LOW (i.e., walking a zero), and the row conductors 31 are monitored one at a time to detect the closure, if any, of switch elements KA-KI as previously described. More particularly, in step 5 310, the first row and the first column, for example, are chosen as the starting point of the reverse scan. It should be apparent to and understood by one having an ordinary skill that the starting point need not be the coordinate (1,1), and may be any other coordinate. As shown in steps 312-316, each of the rows 1 to n (e.g., 1 to 3 in 3x3 switch matrices 10 as shown in the examples of Figs. 1 and 2) are monitored (in step 305) while each column i is driven LOW (step 312). In step 315, a determination is made whether or not all rows have been monitored (or read) by comparing the current row j with the maximum number of columns n, e.g., 3 in the examples of Figs. 1 and 2). In step 308, a 15 determination is made whether or not all columns had been driven LOW by comparing the current column i with the maximum number of columns n, e.g., 3 in the examples of Figs. 1 and 2).

As can be appreciated, the bi-directional scanning switch matrix according to the principles of the present invention may be readily 20 realized by a modification to the scanning algorithm as shown in Fig. 3. A further modification of the scanning algorithm for the embodiment shown in Fig. 2 can be minimized by ensuring that any individual column contains switching elements of the same type, i.e., either push buttons or switches.

Fig. 4 shows another embodiment of the switch matrix 25 according to the principles of the present invention, with a hardware implemented scanning algorithm.

In particular, Fig. 4 shows a switch matrix 40 having three rows and three columns, i.e., a 3x3 matrix.

Each row conductor 31 is connected to an output of a driver 30 37. A driver 37 may be, e.g., a line driver or an open collector amplifier,

etc. Each column conductor 32 is connected to an input of a receiver 36. A receiver 36 may be, e.g., a line receiver or a detector amplifier. The receiver 36 may be Schmidt triggered to account for the direction of transition (i.e., high to low or low to high) of signal at the input of the 5 receiver 36.

Each row conductor 31 and each column conductor 32 are pulled high to a voltage level above the switching threshold of the receiver 36, through a pull-up resistor 38. Typically, the row and column conductors are pulled up to voltage level equal to the supply voltage of 10 the electronics in the device, usually denoted as VCC or VDD.

The pull up resistors 38 must be large compared to the intrinsic resistance in the conductors 31 and 32, and the expected contact resistance of the button 35 and the contacts 33 and 34 in order for proper detection threshold to be reached when keys are depressed. The pull up 15 resistors 38 must also be large in case many keys in the matrix are depressed at once, which effectively places the pull up resistors 38 in parallel.

~~In contrast to a conventional switch matrix, the switch matrix of the present invention may be scanned by applying a level voltage, e.g., level LOW voltage and level High Impedance voltage, no AC noise signal may be present in the conductors 31 and 32. Thus, although the embodiments of Figs. 4 and 5 show optional EMI capacitors 39 for protection against electro-static discharge (ESD) damages, the capacitors 39 are not necessary for proper operation of the switch matrices shown in 25 Figs. 4 and 5. Thus, the present invention provides switch matrices that can be properly scanned without the need for Ac coupling capacitors.~~

The row conductors 31 and the column conductors 32 are arranged and operate similarly as those of the conventional switch matrix shown in Fig. 6 as previously described.

In addition, the switch matrix shown in Fig. 4 has two push buttons and a blocking diode 12 at each coordinate. Thus, the 3x3 switch matrix of Fig. 1 has 18 push buttons KA-KI and K1-K9, i.e., twice the product of the numbers of rows and columns.

5 Although the blocking diode 12 is shown in this example as being connected between switching elements KA-KI and the respective row conductor 31, it should be readily apparent to one of ordinary skill that the diode may be placed in other places, e.g., between the switching elements KA-KI and the respective column conductors 32, or between
10 switching elements K1-K9 and either the row conductors 31 or the column conductors 32 so long as it becomes forward bias when a respective row is driven LOW or when a respective column is driven LOW, but not both times.

15 Fig. 4 further shows receivers 36 on both the row conductors 31 and the column conductors 32 to allow monitoring voltage levels of both the row conductors 31 and the column conductors 32.

20 Furthermore, the switch matrix of Fig. 4 includes outputs of the drivers 37 being connected to both the row conductors 31 and the column conductors 32 to allow driving both the row conductors 31 and the column conductors 32.

Thus, both the row conductors 31 and column conductors 32 of the switch matrix in accordance with the principles of the present invention are bi-directional, and can be either an input or an output, at any given time.

25 The drivers 37 each has a tri-state output, and includes an enable input (shown as a bubble) by which the driver 37 may be enabled to output a predetermined voltage level, or may be disabled to output a high impedance signal, which may be considered as disconnecting the output from the row or column conductors. That is when a driver 37 is

disabled, it appears disconnected (or open) to the respective row or column conductor.

- Each of the selection signals SEL (0), SEL (1) and SEL (2) are produced, for example, under the control of a scanning algorithm for
- 5 scanning the switching matrix of Fig. 1 for a presence of a closure of a switching element KA-KI and K1-K9, and select which driver 37 is to be enabled.

- Driver as &*
- 10 The forward or reverse signal **FOR/REV** together with the selection signals is used to select which driver 37 is to be enabled, and also supplies LOW signal to the input of drivers 37. The OR-Gates 13 ensure that the row drivers 37 are enabled only when both **FOR/REV** signal and the respective selection signal are low, and that the column drivers 37 are enabled only when the inverse of **FOR/REV** signal and the respective selection signal are both low. The inverter 11 inverts the
- 15 **FOR/REV** signal to ensure that the rows or the columns are not both enabled at the same time. The truth table for the **FOR/REV** signal and the selection signals with respect to the selection of a driver to be enabled is shown in Table 1 below.

Table 1

FOR/REV	SEL (0)	SEL (1)	SEL (2)	Driver 37' output of
0	0	1	1	Row 1 LOW, all other Hi-Z
0	1	0	1	Row 2 LOW, all other Hi-Z
0	1	1	0	Row 3 LOW, all other Hi-Z
1	0	1	1	Col. 1 LOW, all other Hi-Z
1	1	0	1	Col. 2 LOW, all other Hi-Z
1	1	1	0	Col. 3 LOW, all other Hi-Z

The scanning algorithm cycles through the above sequence of signals of **FOR/REV**, **SEL (0)**, **SEL (1)** and **SEL (2)** as shown in table 1 above.

5 The blocking diode **12** is reverse biased when the respective row conductor is driven LOW, and the corresponding switching element, e.g., the corresponding push button **KA-KI** is connected. Thus, even if the respective switching element **KA-KI** is connected, the corresponding row conductor **31** and the column conductors **32** remain disconnected to each other.

10 However, when a respective column is driven LOW, and the corresponding switching element **KA-KI** is connected, the diode **12** is forward biased, and thus the corresponding row conductor **31** and the column conductor **32** are connected. When columns are being driven, the voltage driven on the column conductor **32** (less the forward bias voltage drop over the diode which is typically on the order of half a volt) will be placed on the row conductor **31** if the corresponding switching element **KA-KI** is connected. Thus, by monitoring the voltage level of the respective row conductor, a closure of a switch element **KA-KI** may be detected.

15 20 Thus, it can be appreciated that closure of a switching element **K1-K9** can be detected by driving each row, one at a time, and monitoring each of the columns. Because the diode **12** is reverse biased when a row conductor **31** is driven LOW, any closure of switching elements **KA-K9** would not have any effect on the monitored voltages of any of the column conductors **32**. Thus, during this forward scanning (labeling only as a convenience, scanning where only the rows are driven will be referred hereafter as a forward scan, and scanning where only the columns are being drive will be referred as a reverse scan), closure of any of switching elements **K1-K9** can be detected.

During a reverse scan, when a column conductor is driven LOW, the corresponding diode 12 will be forward biased when the corresponding switching element KA-KI is connected, and thus any closure of switching elements KA-KI can be made as described 5 previously.

Thus, during a forward scan, coordinates can be expressed as (Row, Column) as was the case with a conventional switch matrix. However, during a reverse scanning, a coordinate (Column, Row) may be provided. Unlike a conventional switch matrix, in a switch matrix in 10 accordance with the principles of the present invention, a coordinate (Row, Column) is unique from a coordinate (Column, Row).

For example, in a conventional switch matrix, a coordinate (Row =2, Column = 3) and a coordinate (Column = 3, Row = 2) describe the same switching element, namely K6, i.e., the one present at the 15 crossing of the second row conductor and the third column conductor. In a switch matrix in accordance with the principles of the present invention, a coordinate (Row =2, Column = 3) and a coordinate (Column = 3, Row = 2) describe two different switching elements, namely K6 and KF, respectively.

20 By alternating a forward scan and a reverse scan in one scanning cycle as shown in Fig. 4A, all eighteen switching elements can be monitored for their closure.

As shown in Fig. 4A, a complete scanning cycle may include time periods t1-t18, each of which correspond to a reading of a particular 25 row or column conductor 31 and 32 by a corresponding receiver 36 while a particular row or column conductor 31 and 32 is being driven LOW.

For example, during the time periods t1-t9, FOR/REV is low, and the signal from the inverter 11 is HIGH, thus all column drivers 37 are disabled, and appear to column conductors 32 as if they are entirely

absent. Thus, during the time periods t_1-t_9 , a forward scan is performed, i.e., rows are driven and columns are monitored.

During the time periods t_1-t_3 , row 1 (by keeping the selection signals at 011 to enable only the driver 37 of row 1) is driven 5 LOW, and each column is read by the respective receiver 36, e.g., column 1 is read during time period t_1 , column 2 is read during time period t_2 , etc. In this manner status of all nine switching elements K1-K9 are checked during the forward scan period, i.e., t_1-t_9 .

Immediately following the forward scan, i.e., during time 10 periods $t_{10}-t_{18}$, the scanning algorithm would produce a HIGH FOR/REV signal, which disables all row drivers 37 to output high impedance signal. The column drivers 37 are driven LOW, one at a time, and each of the row receivers 36 is read as shown. Because the LOW signal at the cathodes of the diodes 12, the diode 12 is forward biased if the corresponding 15 switching element, i.e., the corresponding one of the push buttons KA-KI, is closed. Thus, when one of the switching elements KA-KI is closed, the corresponding row receiver 36 will read the LOW voltage (with the forward voltage drop of the diode added) when the corresponding column is driven LOW.

20 Thus, switching elements KA-KI are monitored during the reverse scanning period, $t_{10}-t_{18}$, and all switching elements K1-K9 and KA-KI are monitored during a complete scan cycle t_1-t_{18} .

Fig. 5 shows another exemplary hardware embodiment of the switch matrix having integrated persistent connection switches, in 25 accordance with the principles of the present invention.

In particular, Fig. 5 shows a switch matrix 50 identical to switching matrix as Fig. 4 in every respect but having persistent connection switches SWA-SWC in three coordinates of the column 1 in stead of the push buttons KA, KD and KG.

The switch matrix 50 operates essentially as the switching matrix 40 of Fig. 4 despite the inclusion of the switches **SWA-SWC**.

For example, during a forward scan, the switches **SWA-SWC** would not have any affect on the switching matrix because as with 5 switching matrix 50, the diodes 12 would be reverse biased, and the switches would be isolated from the row and column conductors.

During a reverse scan, because only one column driver 37 is enabled at a time, and only one row receiver is read at a time, each of the switches **SWA-SWC** can be uniquely monitored to detect their closure.

10 For example, when **column 1** is driven LOW, and the receiver of **row 1** is read LOW, then the switch **SWA** must be closed, regardless of the status of other switches **SWB** and **SWC**. Thus, closure of any switches **SWA-SWC** can be uniquely detected.

15 It can thus be appreciated that persistent connection type switching elements can be integrated into the same switching matrix alongside temporary connection type switching elements scanned with the same scanning algorithm, without requiring a dedicated scanning or detection mechanism for either the persistent connection or the temporary connection type switching elements.

20 While the switching matrix and method according to the principles of the present invention have been described particularly with reference to a preferred embodiment using an exemplary circuit implementation, the present invention may be implemented with any such variation of the circuits capable of allowing bi-directional scanning of the 25 switch matrix while ensuring alternatively driving and reading columns and rows, i.e., ensuring that both rows and columns are not driven at the same time.

Furthermore, while the switch matrix in accordance with the principles of the present invention is described using an exemplary 30 embodiment showing three integrated persistent connection switching

elements, the present invention may be implemented with any number of such persistent connection switching elements, in any position within the switch matrix, either in the forward scan group or reverse scan group, or monitoring memory access by a processor, and capable of overlaying system and/or user definable information in a faster memory.

While the invention has been described with reference to the exemplary embodiments thereof, those skilled in the art will be able to make various modifications to the described embodiments of the invention without departing from the true spirit and scope of the invention.